

# GOCE

# Preparatory work

## Task 1 : Standards

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# STANDARDS

## REFERENCE SYSTEM

TIME	TT (terrestrial time, ex-TDT) or TAI
CCRS	mean equator and equinox of J2000.0 <sup>1)</sup> (= ICRF)
CDRS	Planetary and lunar ephemerides JPL DE403/LE403 <sup>1)</sup> (or more recent), in TDB (this is IDRF)
Precession	IAU 1976 <sup>1)</sup>
Nutation	IAU 2000 <sup>1)</sup> + IERS (EOP05Cxx) <sup>2)</sup> daily corrections, IERS 2000 (or newer) before 1984
Earth rotation	IERS (EOP05Cxx) daily Earth orientation parameters
CTRS/F	ITRF2000/GRIM5-S2
axis	IERS reference pole and reference meridian
time evolution	No global net rotation
origin	Earth's centre of mass <sup>1)</sup>
SCRF	Spacecraft conventional reference frame (F)
GGRF	* Gravity gradiometer reference frame
Velocity of light	$c = 299792458 \text{ m/s}^1)$
Scale	consistent with TT

<sup>1)</sup> values/models according to IERS Conventions (2000, or updated)

<sup>2)</sup> IERS solution for 2005 and on, version Cxx-tbd

## DYNAMICAL MODEL

Earth

$R = 6378136,46 \text{ m}^1$  (Earth's equatorial radius)

$1/f = 298.25765$  (inverse flattening of reference ellipsoid)

$\omega = 0.7292115 \cdot 10^{-4} \text{ rad s}^{-1}$  (nominal 1994 Earth's mean angular velocity),  $\ddot{\omega} = -4.5 \cdot 10^{-22} \text{ rad s}^{-2}$

$GM = 398600.4410 \text{ km}^3/\text{s}^2$ <sup>1)</sup> (or improved value)

- \* GRIM5-CHAMP initial gravity model (epoch tbd) + time variations (GRACE, tbd).
- \*  $C_{00} = 1^1)$   
 $C_{10} = C_{11} = S_{11} = 0$
- \* solid tides<sup>1)</sup> : anelastic Earth model (Mathews et al., 1995)<sup>1)</sup>, permanent tide not removed
- \* ocean tides : GRIM5-CHAMP (+ GRACE) long wavelength solution + FES 2000.1, (or more recent), completed by long period tides Mtm, Mf, Mm, Sa, Ssa (Lyard 2000 - or more recent), 9.3a, 18.6a equilibrium tides, admittance applied for 60 waves  
non tidal atmosphere mass and load deformation potential (from ECMWF pressure data, every 6h).
- \* Pole tide ( $\tilde{k}_2 = 0.3634$ ), Gegout, 1996

Third bodies

Sun, Moon and planets as point masses, indirect oblateness of Earth/Moon considered, DE403/LE403 ephemerides<sup>1)</sup> (or more recent)

Relativity

Schwarzschild, Lense-Thirring and geodetic precession corrections<sup>1)</sup>

## DYNAMICAL MODEL (cont')

Surface forces (for checking common mode data from gradiometer + drag free info., and for interpolation in gaps)

- atmospheric drag \* DTM 2000 density model (updated with CHAMP data)
- solar radiation \* solar constant  $4.5605 \cdot 10^{-6} \text{ Nm}^{-2}$  at 1 AU<sup>1</sup>), exponential regularising function
- Earth radiation albedo and infrared, monthly geographical mean values (ECMWF)  
Lambert's law
- thermal thrust \* tbd
- empirical accel. \* in data gaps

Spacecraft geometry and thermo-optical properties :

- \* macro-model (facets) and physical coefficients (for drag and pressure) : specular reflection coef., diffuse reflection coef., emissivity, temperature
- \* mass history

## GEOMETRICAL MODEL

<b>Station positions</b>	<b>ITRF2000 (or updated)</b>
<b>Station velocities</b>	* horizontal : ITRF2000 ( $\sigma < 5 \text{ mm/a}$ ), NUVEL1A-NNR <sup>1)</sup> (or updated) vertical : ITRF2000 ( $\sigma < 5 \text{ mm/a}$ ), ICE4G-VM2 <sup>1)</sup> (or updated)
<b>Site displacements :</b>	
geocentre	* empirical annual and semi-annual motions
Earth tides	* anelastic Earth model Mathews et al. (1995) <sup>1)</sup>
ocean loading	based on most recent ocean tide models
atmosphere load.	based on ECMWF pressure data
pole tide	* $\tilde{h}_2 = 0.5133$ (Gegout 1996)
<b>Satellite centre of mass and other parameters (in SCRF) :</b>	
	* c.o.m.
	* position of GPS antenna (phase center) and SLR retro-reflector array
	* star trackers and thrusters (position + orientation in SCRS)
Tropospheric refraction	* Laser : Marini and Murray (1973) <sup>1)</sup> or update , GPS: CNET, Niellis (elevation $\geq 12^\circ$ , or tbd)
Ionospheric refraction	GPS : eliminated in ionosphere-free combination
Relativity	range and Doppler correction (p.p.n. formulation, Sun-Earth-Moon) clock correction : GPS-SST (Martin-Torrence-Misner)
GPS-SST	* ambiguities, clock offsets

(\* - *initial values/models foreseen partly/entirely for adjustment*)