



Jason-1 orbit determination with DORIS and SLR: An alternative approach for accommodating the SAA effect

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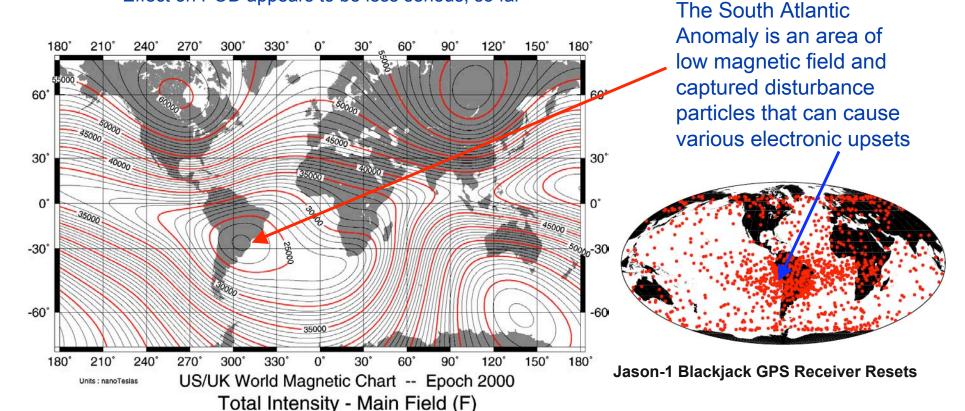
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SAA Effect on Jason-1



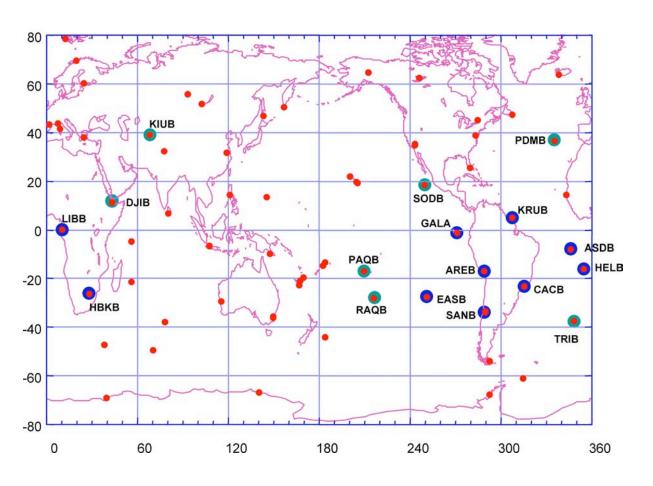
- It is clear that the oscillator on Jason-1 experiences rapid frequency changes during exposure to the increased radiation environment of the SAAΩ
 - Serious effect on station positioning which is becoming progressively worse
 - Strategies to accommodate this being investigated
 - Effect on POD appears to be less serious, so far





Stations Affected by SAA



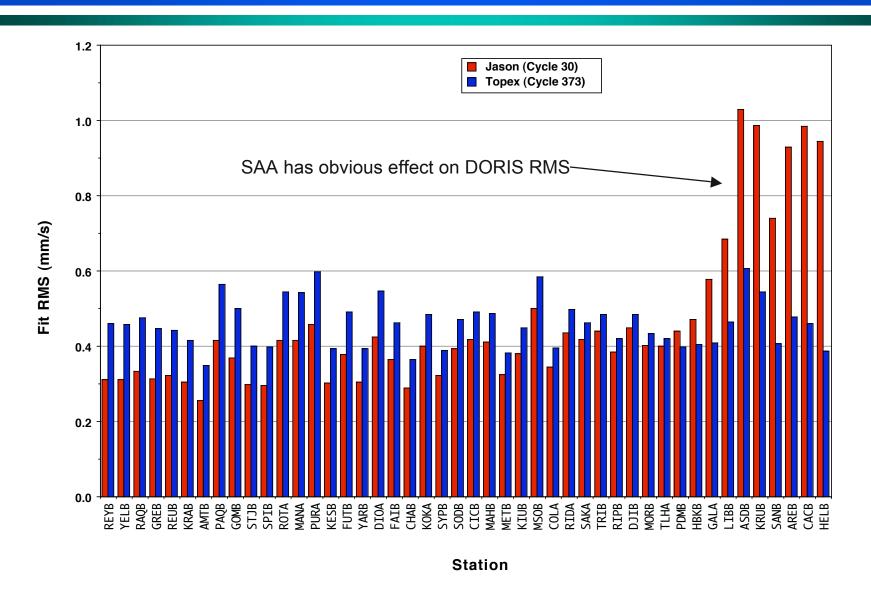


Is the SAA impacting POD accuracy in the long term as the effect increases with time?



DORIS on Jason-1 and T/P







Try Tighter Editing

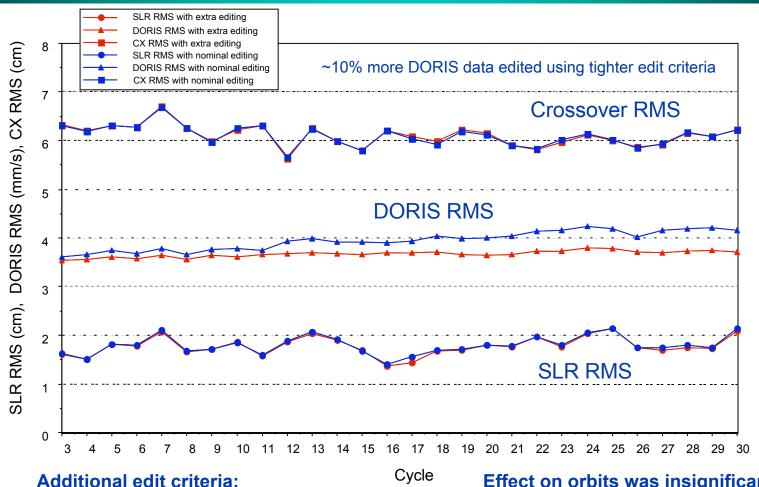


- Using 'Guier Plane' analysis on post-fit residuals, it possible to infer the apparent orbit error along two orthogonal directions: along-track and slant-range (similar to bias and time-bias for SLR)
 - Minimal sensitivity to out-of-plane (cross-track) orbit error; ignored
 - This 'navigation solution' will reflect orbit errors and station coordinate errors, but generally to be dominated by orbit errors
 - The residual frequency offset and troposphere are also estimated
- Passes with large SAA effect have large 'navigation' errors
- Typical editing removes weak, low-elevation passes, passes with large gaps or passes with excess noise, tossing ~9% of the data
 - Tolerance on navigation solutions is quite loose
- Tight editing on navigation solutions (30 cm, 2.5% troposphere)
 leads to the additional loss of another 15% or more of the data
 - Nearly all data from SAA stations is caught and removed
 - Some weaker passes from other sites are also 'caught in the net'



Earlier Results





Pass RMS < 0.6 mm/s slant and tangential navigation errors < 50 cm troposphere errors < 4%

Cycle Effect on orbits was insignificant

Radial rms < 3 mm X,Y,Z shifts < 2 mm

Crossover RMS and mean essentially unchanged



Effect of SSA on Station Navigation Errors



	Cycle 3 (RMS=0.35 mm/s)								Cycle 63 (RMS=0.45 mm/s)						
station		east	std	north	std	ht	std	station		east	std	north	std	ht	std
ADEA	47	2	1	-1	1	0 -1	1	ASDB	2	32	10	-36	1	-98	3
AMTB AREB	26 12	-4 2	2 2	-2 6	1 2	-1 -12	2	CHAB	61	4	2	-2	1	2	1
ASDB	4	-6	9	-4	6	-12 -13	3	CICB COLA	34 28	1 7	2	4	2	3 6	1
BADA	52	1	1	-1	1	1	1	DJIB	31	-2	2	14	3	8	2
CACB	6	-4	4	-19	3	-9	4	EASB	24	-11	6	-40	4	-22	5
CHAB	29	4	1	-1	2	1	1	EVEB	21	-1	2	0	2	6	1
CICB	14	1	1	4	2	-2	1	FAIB	62	1	1	1	1	4	1
COLA	16	2 -2	3 3	3 -3	2	2	1	FUTB	31	-2	3	-4	2	7	1
DJIB	18 25	-2 0	3 2	-3 3	2 2	5 1	1	GREB HBKB	35 29	1 -6	3	-3 -22	3	9 18	2
EASB	23	-2	2	.1	2	3	2	KESB	36	-6 4	2	-22 -8	3	10	2
EVEB	11	<u>-</u> 4	3	1	<u>-</u>	7	- 2	KIUB	40	- 2	2	2	2	5	1
FAIB	50	1	1	-2	1	3	1	KOLB	37	2	<u>-</u>	17	2	4	i
FUTB	19	0	2	4	1	5	1	KRAB	63	4	1	0	1	3	1
GOMB	33	1	1	3	1	1	1	KRUB	11	-18	15	69	6	32	11
GREB HBKB	32 29	1 -3	1	1	1	2	1	LIBB	13	-14	9	41	6	-44	6
HELB	15	-3 3	2	-0 -14	2	-4	2	MAHB	16 59	15	4	, -9	4	1	3
KESB	30	-2	1	-1	2	-1	1	MARB METB	9	-2 8	2	-9 -2	2	0 7	2
KIUB	32	-3	2	-3	<u>1</u>	1	1	PAQB	31	-4	2	-11	3	3	1
KOKA	30	0	1	3	1	-2	1	PDMB	17	-11	4	-6	3	5	2
KRAB	30	2	1	-1	1	0	1	RAQB	30	0	1	-10	2	4	1
KRUB	15	2	1	10	2	-1	1	REUB	34	7	4	-9	3	1	3
LIBB MAHB	14 20	-4 1	2	6	3	-4 2	1	REYB	12	0	3	11	3	-2	2
MANA	20 27	2	2	.1	2	-1	1	RIDA RIPB	32 59	9	6	-15 -1	4	16 18	3
MARB	41	ō	ī	-4	ī	2	i	ROTA	55	8	3	- I 8	3	9	1
METB	39	Ž	1	1	1	0	1	SALB	20	-7	5	28	5	12	6
MORA	20	0	1	-3	2	-1	1	SANB	6	-23	8	-53	16	24	5
MSOB	22	-6	3	-3	3	0	1	SODB	30	3	5	17	2	14	2
PAQB	20	1 2	2	2	1	1	1	SPJB	24	9	2	-6	3	4	1
PDMB RAQB	18 18	-1	2	-5 1	ა 1	3 -4	<u> </u>	STJB	1	2	0	-9	0	4	0
REUB	1	0	0	1	Ó	- -11	0	SYPB THUB	54 31	-2 2	1	5 -2	1	ď	1
REYB	11	-2	1	Ö	1	3	1	TLHA	20	-10	4	- <u>-</u> 1	3	4	2
RIPB	48	-1	1	-1	1	3	1	TRIB	33	-19	6	-6	3	- 18	3
ROTA	43	0	1	-2	1	3	1	YARB	40	5	1	-1	2	1	1
SANB	20	1	1	-11	2	-3	2	YELB	61	3	1	-2	1	6	1
SODB	25	1	2	5	1	3	1								
STJB SYPB	37 34	-1 -1	1	-2 0	1	-1 0	1	_							
TLHA	30	1	1	2	1	0	1	Th	e worst	t is not	repres	ented h	ere; so	ome	
YARB	31	Ö	i	<u>-2</u>	i	-1	i				-				
YELB	49	Ö	3	-3	3	-2	1	Sta	uons n	or ever	ı passı	ng CNE	s edit	irig	



Effect of Editing on Navigation Errors



Cycle 63 Nominal Editing (RMS = 0.45 mm/s)

•			•			•
# pass	east	std	north	std	ht	std
					-98	3
		2	- <u>2</u>		2	1
		2	4	2	3 6	1
	-2	2		3	8	2
24		6		4	-22	1 2 5
21	-1	2	0	2	6	1
62		1	1			1
		3	-4	2	7	1
		3	-3	3	9	2
		5	-22	ა ე	18 1	2 2 2
	-2	2	-0 2	2	5	1
	2	2	17	2		i
63	4	1	0	1	3	1
11	-18	15	69	6		11
	-14	9				6
					1	3
	-2	2	-9	2		1
		2	- <u>-</u> 2 -11	3	3	1
		4	-6	3	5	ż
30	Ö	1	-10	2	4	<u>1</u>
34	7	4	-9	3	1	3
		3				2
		6	-15	4	16	6 3 1 2 1 2 1 3 2
		4		ა 2		1
	-7	5	28	5	12	6
	-23	8	-53	16		6 5 2
30	3	5	17	2	14	2
24	9	2	-6		4	1
	2		- <u>9</u>		4	0
	-2		5		8	1
	∠ -10	•	- <u>∠</u> 1		<u> </u>	1
				3		1 2 3
				2		1
61	3	1	-2	1	6	1
	2 61 34 28 31 24 21 62 31 35 29 36 40 37 63 11 13 16 59 31 17 30 34 12 32 55 50 6 6 30 24 1 5 5 5 6 6 7 7 8 8 8 8 8 9 8 9 8 9 8 9 8 9 8 8 9 8 8 9 9 8 9 9 9 9 9 9 9 8 9	2 32 61 4 34 1 28 7 31 -2 24 -11 21 -1 62 1 31 -2 35 1 29 -6 36 4 40 -2 37 2 63 4 11 -18 13 -14 16 15 59 -2 9 8 31 -4 17 -11 30 0 34 7 12 0 32 9 59 1 55 8 20 -7 6 -23 30 3 24 9 1 -2 20 -10 33 -19 40 5	2 32 10 61 4 2 34 1 2 28 7 2 31 -2 2 24 -11 6 21 -1 2 62 1 1 31 -2 3 35 1 3 29 -6 5 36 4 3 40 -2 2 37 2 2 63 4 1 11 -18 15 13 -14 9 16 15 4 59 -2 2 9 8 2 31 -4 2 17 -11 4 30 0 1 34 7 4 12 0 3 32 9 6 59 1 4 55 8 3 20 -7 5 6 -23 8 30 3 5 24 9 2 1 2 0 5 54 -2 1 31 2 0 1 32 9 6 59 1 4 55 8 3 20 -7 5 6 -23 8 30 3 5 24 9 2 1 2 0 5 54 -2 1 31 2 0 1 32 9 6 59 1 4 55 8 3 20 -7 5 6 -23 8 30 3 5 24 9 2 1 20 -10 4 33 -19 6	2 32 10 -36 61 4 2 -2 34 1 2 4 28 7 2 1 31 -2 2 14 24 -11 6 -40 21 -1 2 0 62 1 1 1 31 -2 3 -4 35 1 3 -3 29 -6 5 -22 36 4 3 -8 40 -2 2 2 37 2 2 17 63 4 1 0 11 -18 15 69 13 -14 9 41 16 15 4 7 59 -2 2 -9 9 8 2 -2 31 -4 2 -11 17 -11 4 -6 30 0 1	2 32 10 -36 1 61 4 2 -2 1 34 1 2 4 2 28 7 2 1 3 31 -2 2 14 3 24 -11 6 -40 4 21 -1 2 0 2 62 1 1 1 1 31 -2 3 -4 2 35 1 3 -3 3 29 -6 5 -22 3 36 4 3 -8 2 40 -2 2 2 2 37 2 2 17 2 63 4 1 0 1 11 -18 15 69 6 13 -14 9 41 6 16 15 4 7 4 59 -2 2 -9 2	2 32 10 -36 1 -98 61 4 2 -2 1 2 34 1 2 4 2 3 28 7 2 1 3 6 31 -2 2 14 3 8 24 -11 6 -40 4 -22 21 -1 2 0 2 6 62 1 1 1 1 4 31 -2 3 -4 2 7 35 1 3 -3 3 9 29 -6 5 -22 3 18 36 4 3 -8 2 4 40 -2 2 2 2 5 37 2 2 17 2 4 40 -2 2 2 2 5

units are cm

Cycle 63 Tight Editing (RMS = 0.36 mm/s)

Up to 30% of the data is removed using tight editing on station navigation solutions

Systematic height bias remains due to effect of frequency drift model, which must accommodate both SAA and non-SAA drifts

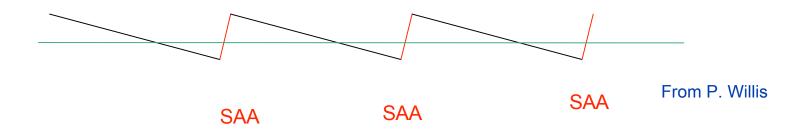


Indirect Effect of SAA on 'non-SAA' Data





Jason-1 satellite clock in DORIS data (after removal of a long-term polynomial by CNES)



When the SAA effect was smaller, the impact on 'non-SAA' data was negligible

As SAA effect increases, however, the induced slope on 'non-SAA' data becomes a problem

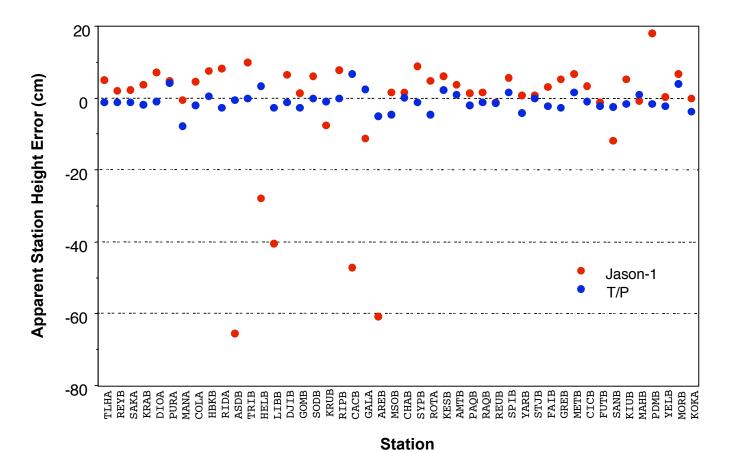
Can problem for non-SAA stations be addressed with a global bias-drift parameter? (effect is not station dependent; it is common to all non-SAA stations through clock model)



Geodetic Consequences



- There is a systematic error in the frequency model used to scale phase to range that is the result of the SAA effect, which is affecting all DORIS data from Jason-1
 - All stations outside of affected area have height errors which are biased in the opposite sense
 of the affected stations





Effect of Global Bias-Drift Parameter



Cycle 63 Tight Editing Only (RMS = 0.36 mm/s)							units a	are cm	Cycle 63 Tight Editing and Global Drift (RMS=0.35 mm/s)						
Station CHAB CICB COLIB EVEB FUTB GRESB KIUB KOABB MARB MARB MARB MARB PAQB REYBA RIDA RIPA RODB SYPB TILHB YARB	# pass 45 23 25 19 58 26 28 27 327 58 13 48 6 23 21 45 20 15 24 56 25 15 24 56	east 4 1 4 3 2 1 1 0 7 -3 2 4 7 0 12 -2 -4 0 3 8 -8 -6 0 -1 14 -1 2 -7 0 4 2	std 1 1 2 2 2 1 1 1 2 1 2 1 2 6 2 1 1 3 2 1 2 3 2 1 1	north -1 4 1 7 3 0 -3 0 -7 0 13 0 4 -6 2 -10 -6 8 1 -8 -4 -7 3 14 -7 5 -5 -1 -4 1 -2	std 12233122212142323321114113221	ht2258646865533893443-19106127935916	std 1 1 1 1 1 1 1 1 1 1 2 1 1 1 1 2 1 1 1 1 2 1 1 1 1 2 1	Station CHAB CICB COLA DJIB EVEB FAIB FUTB GREB KOLB KRAB MAHB MARB METB PAQB PDMB REUB REYB RIDA RIDA RIDA SPJB SYPB THUB TLHA TRIB YARB	# pass 23 10 58 26 27 33 7 58 22 45 36 22 45 36 22 45 36 22 56	ea 4 0 2 -2 3 0 0 0 2 -1 2 1 5 -1 3 -2 -1 -1 10 -6 -6 -1 -4 6 -3 -3 -6 -4 3 2	std 112111222121211521122123211	north 2 3 2 10 2 2 3 3 5 1 11 -2 2 3 -2 10 -6 -6 3 3 -6 -4 2 13 3 2 1 0 -2 1 -1	std 11232122211131423234211114123211	h3-3042-203200-2033-31-10-4541834-104-40	std 1 1 1 1 1 1 1 1 1 1 1 1 1 2 1 2 1 1 2 1 1 2 1 1 2 1 1 2 1 1 2 1 1 2 1 1 2 1 1 2 1 1 2 1 1 2 1 1 2 1 1 1 2 1 1 1 2 1 1 1 1 1 2 1 1 1 1 2 1 1 1 1 2 1 1 1 1 1 1 2 1 1 1 1 1 1 2 1 1 1 1 1 1 1 1 1 1 1 2 1
Average		2		-1		5		Average		0		0	-	1	

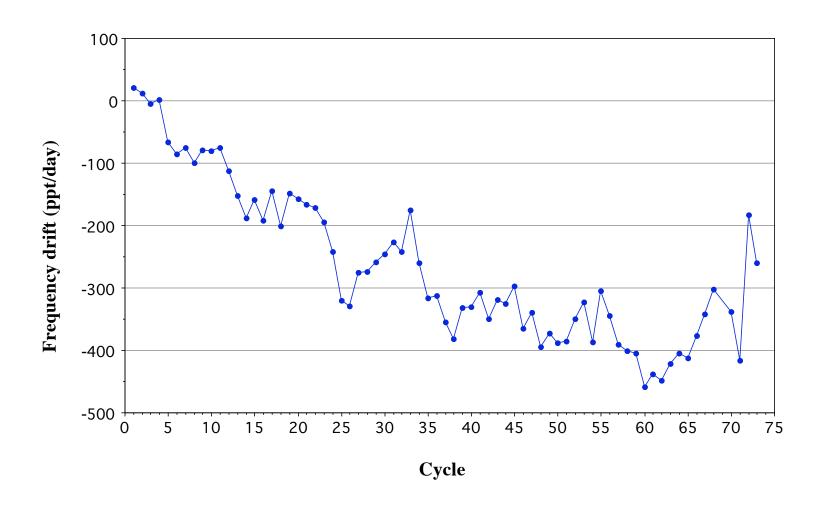
Bias in all 3 components has been reduced or removed through a single extra parameter

Note: bias-drift parameter CANNOT be used if data affected by SAA are not edited



Bias-drift vs Time







Impact on POD



- In spite of strong SAA effect on fits, POD is only slightly affected (in the case of these 10-day dynamic orbits; reduced-dynamics will be much more affected)
 - Strong editing of affected stations provides only modest orbit improvement
 - Adding a global bias-drift parameter has an insignificant effect on orbit quality
 - Removes systematic error in residuals that looks like station height error (leading to slightly better fits)
 - High correlation (0.8) with station height estimation; cannot be used for positioning

CASE (Cycles 68, 73)	SLR RMS (mm)	DORIS RMS (mm/s)	CX RMS/Mean (mm)	Z-shift (mm)	Radial RMS diff (mm)
Normal edit,	14.9	0.430 (72213 obs)	58.1 / 6.9	+8	11.4
no bias-drift	16.4	0.485 (78642 obs)	60.4 / 0.7	-9	11.9
Strong edit,	14.5	0.347 (55536 obs)	58.0 / 5.2	+8	11.2
no bias-drift	15.5	0.354 (55213 obs)	59.8 / 0.6	-9	11.6
Strong edit,	14.4	0.342 (55536 obs)	58.0 / 5.0	+8	11.2
global bias-drift	15.4	0.351 (55213 obs)	59.8 / 0.4	-9	11.6

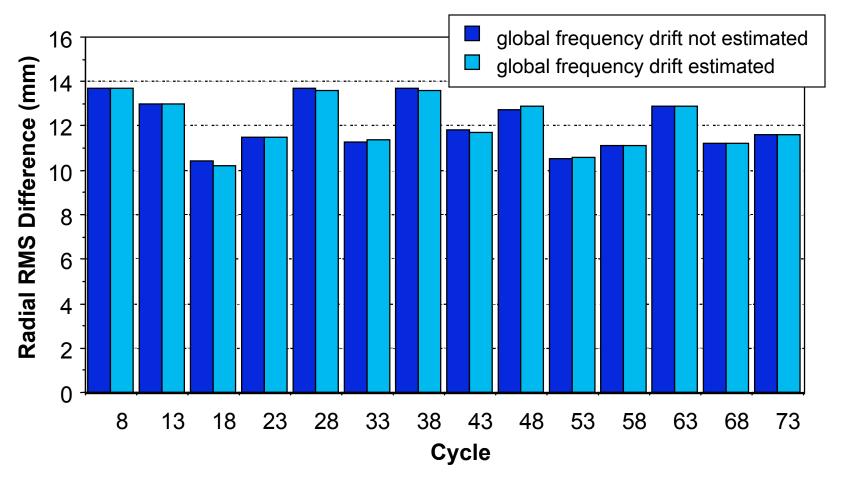
(note: results based on using GGM01S; orbit comparisons relative to JPL GGM01S orbits from B. Haines)



Comparison with GPS Orbits



Average difference RMS identical at 12.1 mm with GGM01S (13.7 mm with JGM-3)



No discernable benefit from including bias-drift parameter for POD



Conclusions



- South Atlantic Anomaly has dramatic effects on data quality for stations in the vicinity
 - Geodetic applications (position/velocity estimation) severely affected for SAA sites
 - Indirect effect on remaining sites through clock model
 - Adding bias-drift parameter can absorb clock model error but is correlated with station heights (correlation coefficient of ~0.8)
- Impact on long-arc orbits is small
 - Some benefit seen with strong editing applied
 - Adding bias-drift parameter improves fits slightly but orbit accuracy not significantly improved



Additional Notes: Troposphere Estimation



Troposphere estimation is typically of the form

$$\square (H_{dry} + H_{wet})_Z f(\square)$$
 or $H_{dry} + \square H_{wet} f(\square)$

where [] is the scale factor and f is the mapping function

- If pressure measurement is reliable, latter formulation may be more effective (GPS, PRARE)
 - Q: Is meterological information from DORIS stations reliable?
 Are the equipment monitored or calibrated regularly?
- Typically, no apriori constraint is applied to
 - This is pessimistic...assumes no confidence in model
 - Early station estimation with DORIS for T/P showed considerably improvement in results using significant apriori constraint on troposphere parameter (few percent)



Additional Notes: Time Bias



- DORIS timing bias on T/P is currently 10-11 microsec; 5-6 microsec on Jason-1 (Envisat?)
- Time bias on SPOT satellites is an unknown
- May average N-S at any location but could have a non-zero E-W component (probably only significant for T/P)
- What is impact on positioning if time bias is not removed?